



Warts, Bumps, and Blemishes

Experimenting with Sensor Webs Using EO-1 2 March 2004



Stuart Frye Mitretek Systems

EO-1 Systems Engineer

EO-1 Sensor Webs/GSFC System Engineering Seminar



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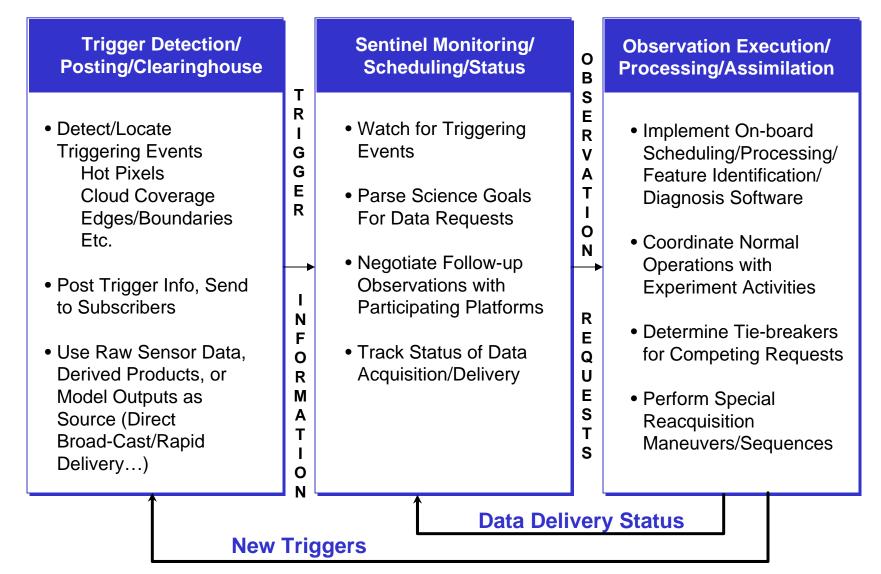


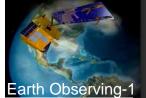
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EO-1 Sensor Web Functions

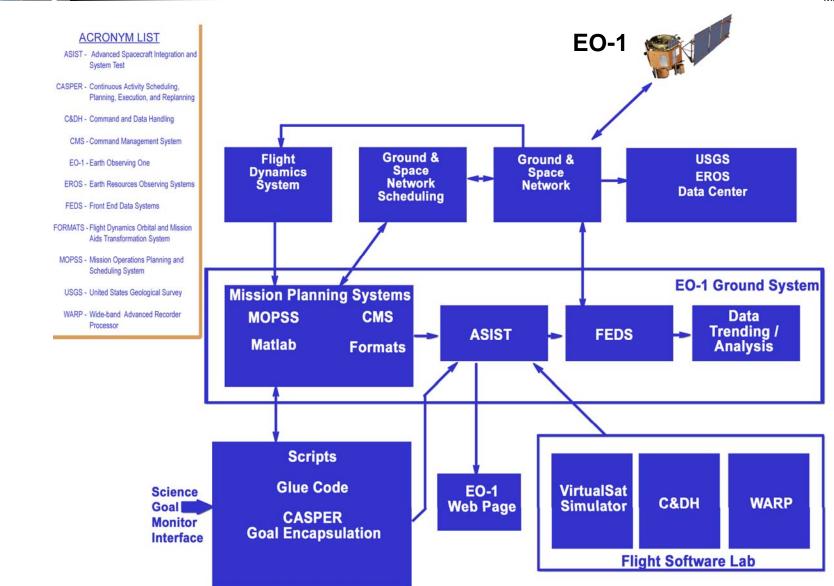






EO-1 Mission Systems







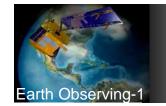
Automated Sequence Generation



- Mission goals
 - E.g. image Kilauea (Lat/Lon)
- ◆ To Command Sequence

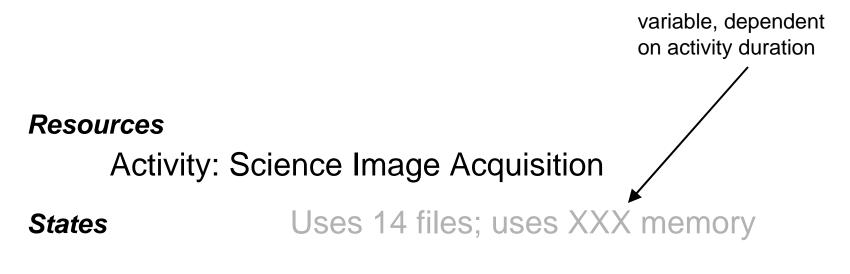
2003:233:16:49:57 CMD ACSETWHLBIAS(INERTIAL,X=0.341589,Y=1.1749,Z=-0.118046); 2003:233:17:56:57 CMD ACGOTOMANEUVER(ORBITAL,TIME=900,XLIMDEG=0.02,YLIMDEG=0.062699,...); 2003:233:18:07:06 CMD I_SETFPEPOWER(POWER_MASK=5); 2003:233:18:07:06 CMD YHEASTBY; 2003:233:18:07:16 CMD YHEASETSWIR(GAINA=1,GAINB=1,GAINC=1,GAIND=1,...); 2003:233:18:07:26 CMD YHEASETVNIR(VNIRALV8,VNIRBLV8,VNIRCLV8,VNIRDLV8); 2003:233:18:11:06 CMD I_CONFIGFPE(CONFIG_COMMAND=16908); ... 2003:233:18:17:06 CMD BCMMODESCRS422; 2003:233:18:17:16 CMD WRMSREC(IDWS=65535,IDWV=65535,...); 2003:233:18:17:54 CMD I_SET_FPE_DG(DURATION=-1);

• • •



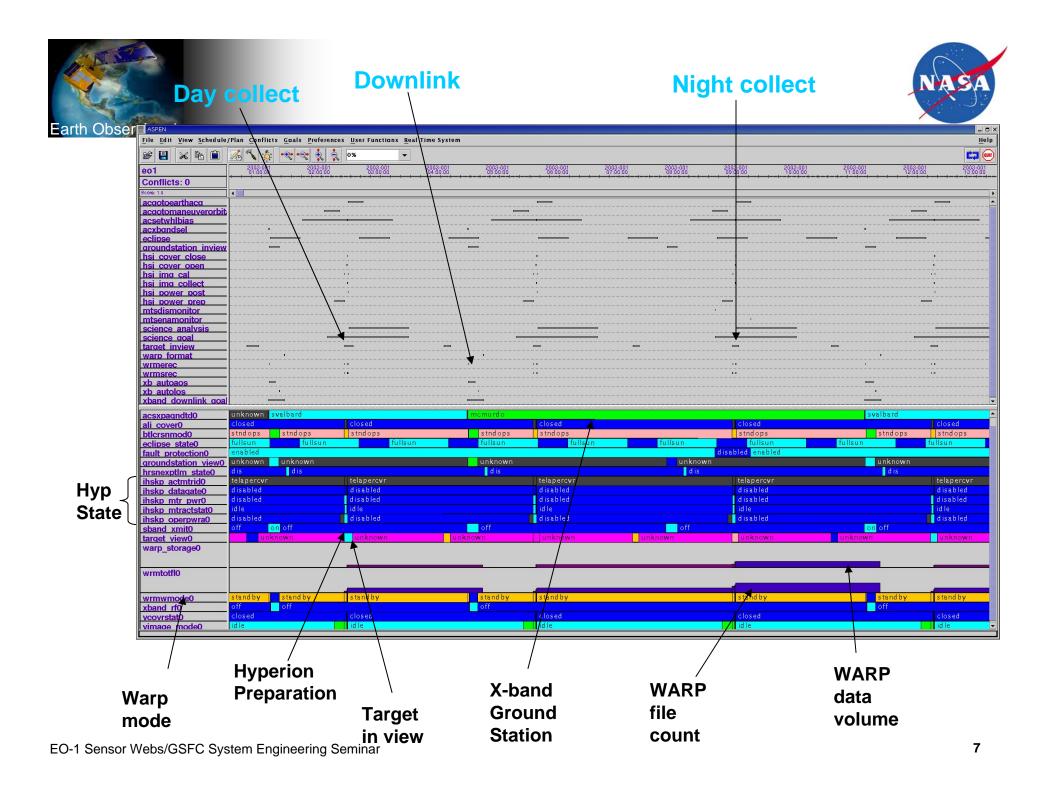
Uses Model of Activities

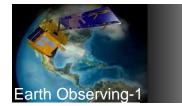




Other Activities requires target pointing

These models are then combined to model the world as it changes due to activities

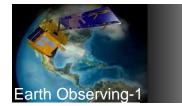




CASPER Planning

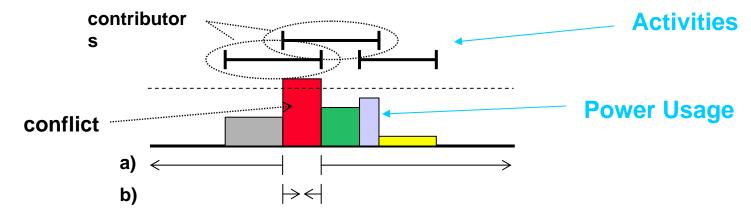


- CASPER can implement nominal procedures through decompositions (similar to scripts)
 - In order to image: do x, then y, then z...
- CASPER can also perform planning "from scratch" via search
 - If want ACS-mode state variable = standby, consider adding an activity that changes ACS-mode (then the requirements of these activities may be new conflicts,...)
 - Most commonly used search framework "iterative repair"

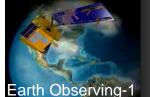


Activities, Constraints, Repairs





Constraint	Property that must hold for plan to be valid	<i>Must always use less power than available</i>
Conflict	Violation of a constraint	<i>Current plan uses more power than available from 18:00-18:30</i>
Repair Method	Modification to plan that may remove conflict	Delete activity using power during conflict
Repair Choice	Which activity to delete	Delete largest user?

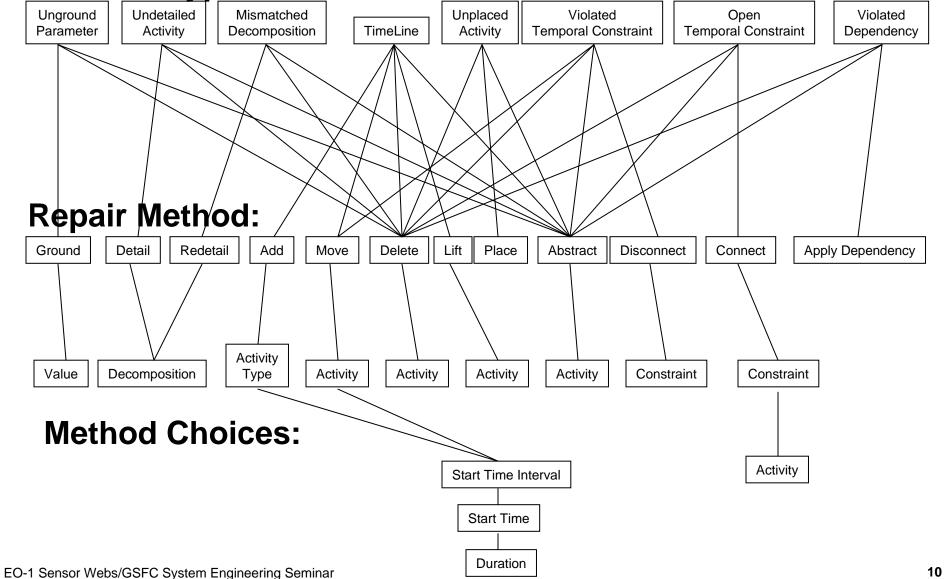


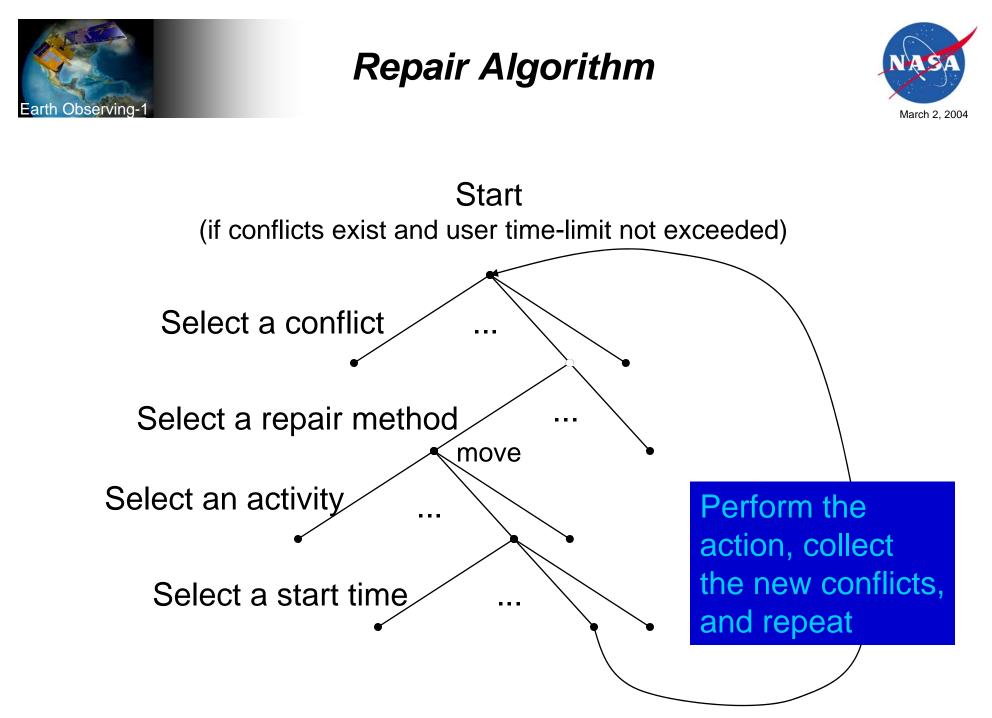
Constraint Resolution Tree



ann Observing-I

Conflict Type:

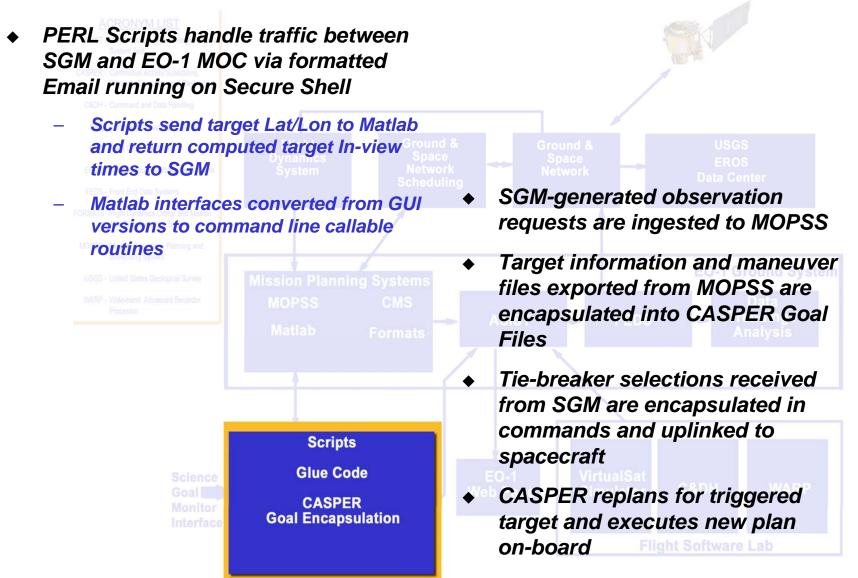


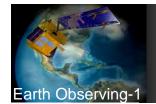




Interface Scripts and Glue Code







New Mission Planning Activities



•	Experiment Time Slots Need to be Integrated into Commercial Observation Schedule for Every Experiment	 Exported Sequences Are Removed from MOPSS Command Load Overlap Between Exported 	
•	Placeholder Target and Comm Requests Are Inserted to Pre- Populate Schedule	CASPER Sequences and Command Load Sequences Are Verified/De-Conflicted	
 ♦ 	SGM-generated RecordsAre Ingested and Placeholders OverwrittenMission Planning Systems MOPSSMission Planning Systems MOPSSCMS FormatsImage SequencesMatlab	 Including Verifying Continuity of Scene Information from Exported Sequences in Load Reports for Downstream Antenna Operations, Science Data Processing, and Scene Tracking Systems 	
	Are Exported as Input to Goal File Generation Scripts for CASPER- Scheduled Requests	 Need to pick which comm contact to use to load/jump to new on-board code to avoid other overlapping operations on processor 	

Don't forget to push the blue button at 8:07GMT



Ground System Accommodations/Upgrades



Data Trending /

- Created new procedures for sending sensor web triggers to spacecraft, loading new code on-board, jumping to new executables
- Modified command uplink acknowledgement scheme and timeout settings to handle large code uploads
- Modified command database for new autonomy commands
- Modified telemetry database for new autonomy telemetry
- Modified Systems Test and Operations Language (STOL) procedures to perform code load, checksum, uncompress, jump, goal/script activation, WARP reset



FEDS

ASIST

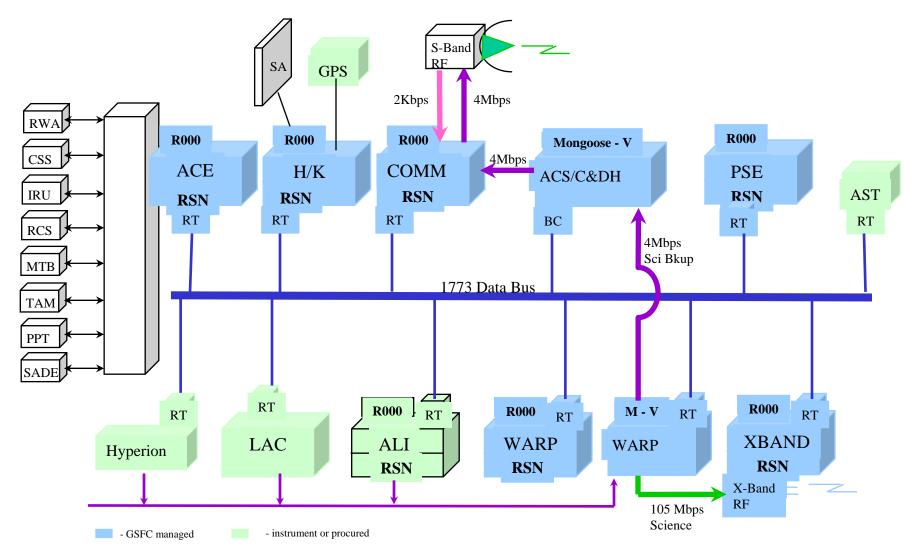
- Modified max slew rate from .25 to .433 deg/sec (Re-image scenario)
- Increased number of retransmit entries in FEDS command queue
- Upgraded trending system to pickup new telemetry mnemonics

No, not THAT blue button!



FSW Overview (Block Diagram)

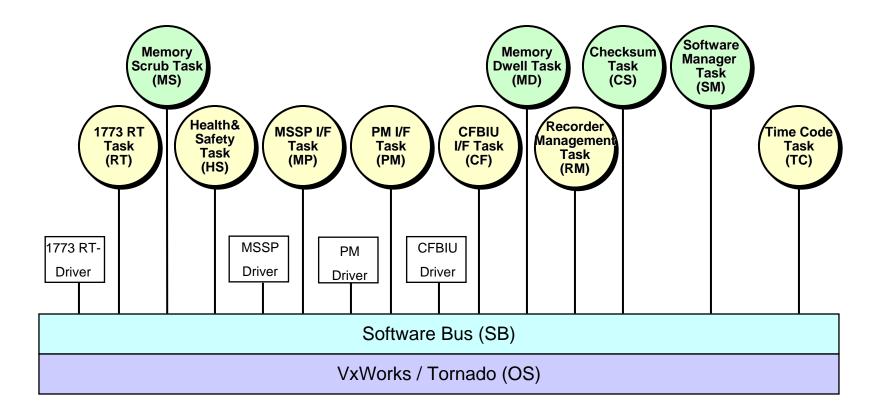






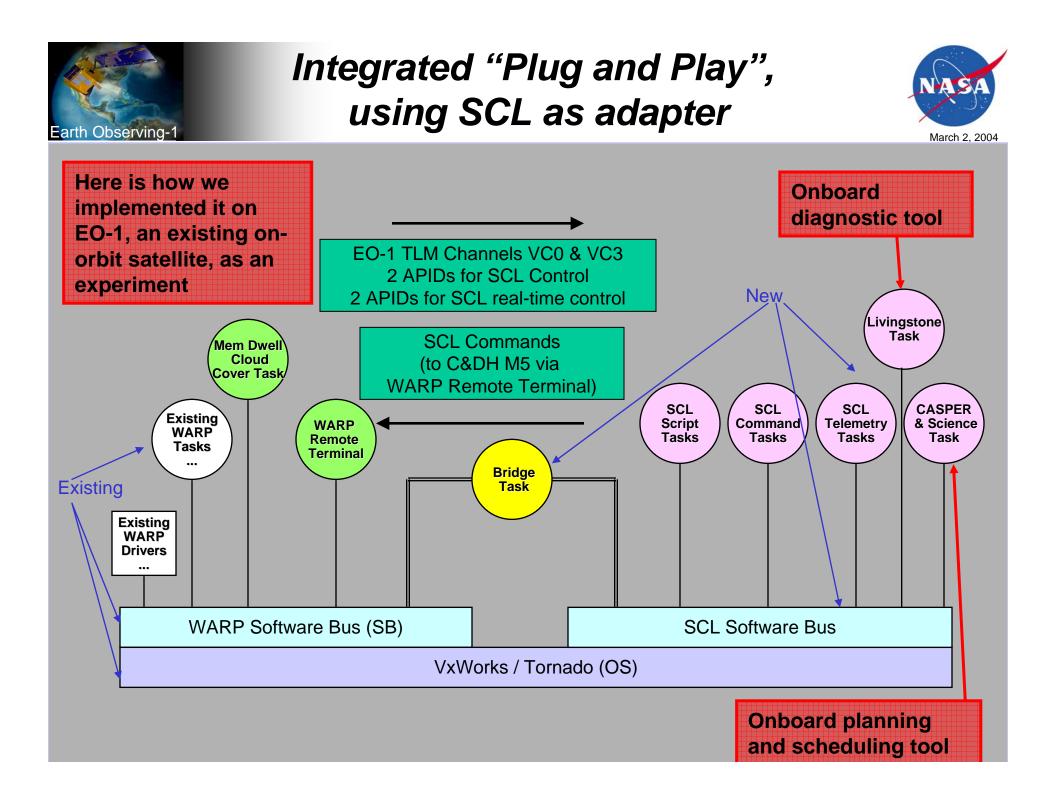
WARP Software Architecture

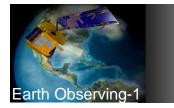






Newly Developed Task for EO-1 WARP Re-Used Task from MIDEX/MAP





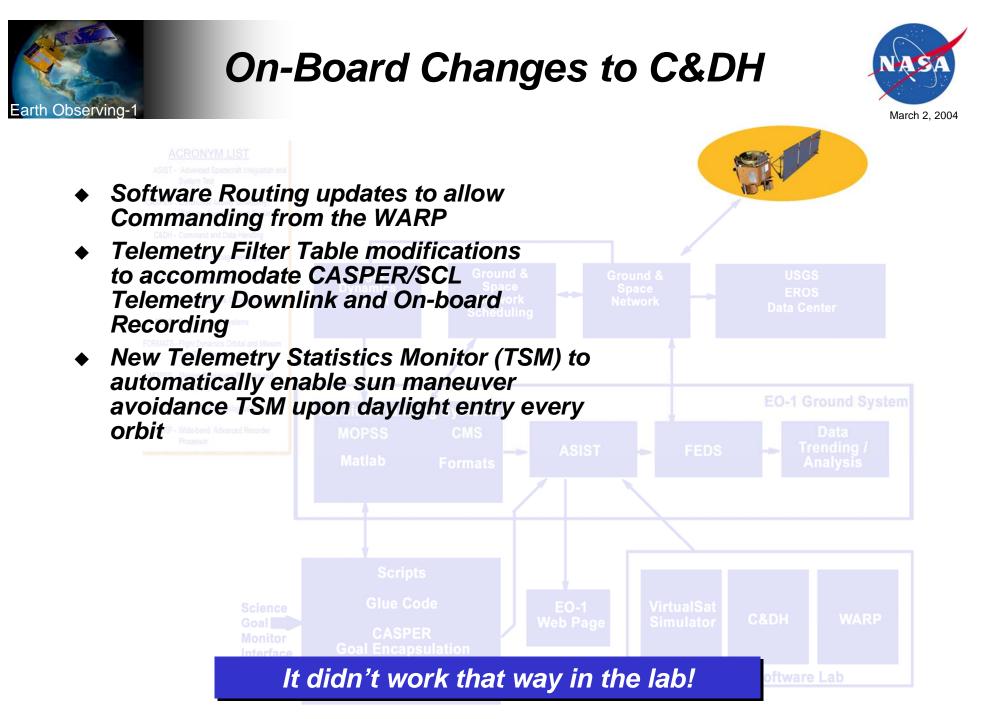
Flight Software Lab



- Developed capability to reload WARP Flight Software kernel and patch to boot from new image using hijacked existing command
- Developed C&DH patches (next page)
- Integrated Spacecraft Control Language (SCL) and CASPER spacecraft autonomy software with WARP flight code
 - Developed utilities for encapsulating executables into S records for memory load STOL commands
- Upgraded VirtualSat to simulate additional command, telemetry, and event message traffic
- Implemented remote access for integration work via (Tight) Virtual Network Computing
- Implemented file transfers for code loads via Secure Shell
- Developed ability to compress and decompress executable code loads to reduce uplink bandwidth requirements
- Procured and integrated two additional test strings
 - 2 C&DH Mongoose 5, 2 WARP Mongoose 5,
 2 VirtualSat simulators, 1 Spare Mongoose 5

Now I see why they didn't fly that board!







On-Board Changes to WARP

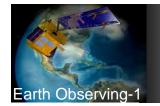


ACRONYM LIST

- Reloaded entire WARP code image and jumped to it via patch
- Modified Memory Dwell task and S-band playback function in WARP Flight Code to read science data into RAM from near-line bulk storage
- Created various SCL and CASPER-related tasks
- Hijacked telemetry packets and commands for SCL and CASPER use
- Loaded new CASPER, SCL and cloud assessment algorithm on-board

- Added Event Messages for status reporting
- Modified checksum configuration on WARP for upload verification
- Increased WARP Watchdog timeout to prevent reset when booting to new larger code
- Turned Off CPU hogging and changed Memory Dwell task check-in error to an event – had caused warm restart
- Implemented a decompression utility on-board based on zlib library inflate function

Explain to me again why I can't playback science data over S-band or run memory diagnostics with CASPER running



System Engineering Issues



- CASPER knows spacecraft state and resources
 - Doesn't do navigation, orbit propagation,...
 - Doesn't do momentum management/maneuver planning
 - Has to coordinate file naming conventions with Command Load observations
 - Changeover from Command Load to CASPER control
- Better coordination required because more complex activity sequences are being undertaken
 - Operational sequences are not independent



Warts (1 of 3)



- FSW lab hardware not identical to flight hardware
 - WARP Flight Processor has 256Mbytes RAM, but breadboard in lab has 32M memory for integration work – limits use of full on-board memory
 - Off-line WARP bulk memory cards not procured for EO-1 lab (>\$1M) limits testing for image data file manipulation code
 - Insufficient memory in Flight Software Lab Breadboard caused several month delay in integration effort
 - Sensors and Mechanisms simulated using VirtualSat
- Cannot duplicate on-board dynamics in lab (e.g., CPU starvation)
- Unexpected spacecraft reactions encountered during experiments
- On-orbit debugging required
- Had to use outgassing periods every 16 days to run experiments
 - Always a stretch to define scope, schedule support, deliver tested code and unzip/jump/verify procedures in time for uplink



Bumps (2 of 3)



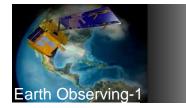
- Code loads to testbeds in FSW Lab slow at first sped up by implementation of ICEPROMS and/or Ethernet on Mongoose boards
- Takes 3-4 days to uplink code loads to spacecraft
 - 15-20 ground station contacts
 - TDRS not reliable for large uplinks can only use ground stations
 - 6Mbyte code loads to spacecraft compress by about 6-1
- Encountered problems verifying large uplinks
 - Not enough time to do full dump and compare
 - Using checksums was labor intensive and discrepancies hard to isolate
 - Made for some exciting tests....
- WARP reboots during dumps causes dump flag to hang on C&DH
 - Had to stuff WARP dump bit to YES, then send abort to clear C&DH flag
 - Still ran experiments on non-verified code Oh Well!



And Blemishes (3 of 3)



- On-board Cloud Detection takes 15 minutes to run on-board
 - Not sufficient for look-ahead/assess/retarget scenarios
 - Next load of FSW will allow selectable readout of hyperspectral bands and selectable readouts of particular rows of the image data file to speed up
- Special care has to be taken to avoid invoking on-board memory operations during command load event windows
 - No code loads, script updates, dumps, jumps, or other activation/deactivation memory operations during WARP Record or Playback events
- Crashed WARP once memory starvation issue
 - Spacecraft was under CASPER control
 - Crash occurred during image sequence Watchdog check-in
 - Left spacecraft maneuvered with instruments on and covers open
 - Had to recover manually during next communications contacts



Lessons Learned



- Build excess CPU and memory capacity into Flight Segment
 - Enables sensor web/autonomy improvements post-launch
- Include at least 2 flight processors on-board in future designs
 - Can do development work without disturbing C&DH operations
 - If 2nd processor is not executing new FSW properly, reboot to old code
- Build ground FSW Lab with identical hardware to Flight Segment
- Minimize time spent on development of support tools and utilities during early part of software effort
 - Concentrate on primary functionality until better tools would save time
- Learn through failure if it's safe to do so if you wait until you're 100% sure of success, you may never get anything done
- Setup safeguards to auto-recover via command load after crashes are encountered during experiments
- Need to setup process for delivery of science data from experiments - problematic in commercial data sales setting